

# 가 (GMFM)

## Abstract

### **The Relevance Between Gross Motor Function Measurement (GMFM) and the Spatiotemporal Parameters of Gait in Children With Cerebral Palsy**

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This paper presents the relevance between GMFM and the spatiotemporal parameters of gait in children with cerebral palsy.

Twenty-one children ( $73.11 \pm 30.06$  months) with cerebral palsy participated in this study. GMFM was performed and spatiotemporal parameters of gait were measured by foot print gait analysis. A correlation analysis was used to investigate the correlation between GMFM scores and spatiotemporal parameters of gait. A linear regression analysis was employed to find how much each gait spatiotemporal parameters could be predicted from GMFM scores. The total GMFM scores was significantly correlated with walking speed, cadence, and stride length. Dimensions D (standing) and E (walking, running, and jumping) were more significantly correlated with gait spatiotemporal parameters than dimensions A (lying and rolling), B (sitting), and C (crawling and kneeling). The GMFM scores were useful for predicting spatiotemporal parameters. However, it is difficult to predict the status of gait development using GMFM scores because GMFM scores and gait spatiotemporal

parameters are only measured as quantities not qualities.

In the field, it is easily found that many children with cerebral palsy are unable to walk in any way. Consequently, gait analysis cannot be performed in many cases. Therefore, it is more reasonable to investigate the influence of GMFM on spatio-temporal parameters, rather than vice versa.

**Key Words :** Cerebral palsy; GMFM; Spatiotemporal parameters; Gait.

(motor skill)

(Drouin (Damiano Abel, 1996). 가 1996). 가 GMFM (Damiano Abel, 1996). 가 GMFM 가 (Damiano Abel 1996), GMFM D ( ), E ( , , ) 가 (locomotor predictor) (Drouin , 1996). Kramer MacPhail(1994) GMFM (isokinetic strength) 가 가 Parker (1993) 23 (spatiotemporal measure; STM) 가 GMFM , foot print . Drouin (1996) 가(videographic test; 26 4 VGT) (Drouin , 1996). 가(Gross Motor Func- , GMFM tion Measure; GMFM) GMFM D, E (motor status) GMFM 가 가 45 cm/s 가 (motor function) , Abel (Damiano Abel, 1996). 가 Damiano(1996) 가 가

Damiano Abel(1996) , 32  
 GMFM  
 (gait para- meters)  
 가 GMFM  
 가 , , 가 , 가  
 GMFM  
 (selective posterior rhizotomy; SPR)  
 ( , 1993; , 1997)  
 가  
 가 , 가  
 GMFM  
 foot print  
 GMFM  
 가  
 21  
 ( , 1999),  
 가  
 (walker)  
 1994).  
 가 , , foot print  
 가 , (Drouin , 1996).  
 Wolf(1979)

2.

2.  
 GMFM (motor status)  
 가 (motor function)  
 (Damiano Abel, 1996), Palisano (2000)  
 GMFM , 가 .91  
 , Nordmark (1997)  
 GMFM  
 .77, - .88,  
 .68 GMFM  
 가  
 가  
 가  
 가 , 가  
 가 5 , A( ), B  
 ( ), C( ), D( ), E  
 ( , , ) , 88  
 , A 17 , B 20, C 14, D 13,  
 E 24  
 /가 × 100'  
 가 ,  
 5 GMFM .

1.

Clarkson(1983), Holden (1984), Shores (1980) foot print

Drouin (1996) foot print

가 (Russell, 1993).

foot print

3. 800 cm, 60 cm

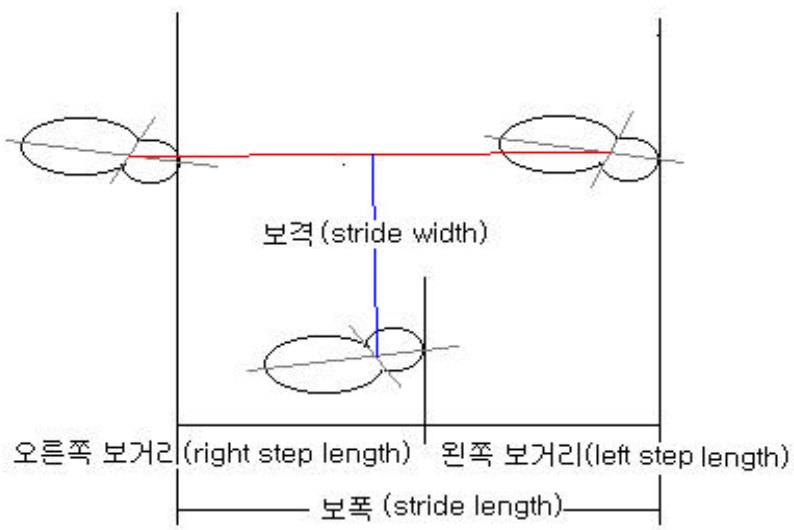
가 cm 가

cm (, 1996).

GMFM

2 가 가 가 가 cm

150



1. Foot Print

(heel contact) 150 cm  
 가 (toe off) Pearson

(step-wise multiple linear regression analysis)  
 150 cm 500

cm (1996).  
 Shores(1980)가 GMFM  
 foot print Boenig(1977)가 foot print  
 (1). (Spearman correlation co-efficient)  
 가 (gait velocity): GMFM  
 t- (independent t-test)  
 m/s  
 (cadence): GMFM  
 (step) foot print  
 steps/s (1994).  
 (stride length): Spearman  
 GMFM  
 가  
 t- (independent t-test)  
 m  
 (left step length):  
 m  
 (right step length): 1.  
 21 ( 15 , 6 )  
 13 (61.9%),  
 m (stride width): 가 6 (28.6%), 2 (9.5%)  
 가 가 10 (47.6%),  
 가  
 11 (52.4%) ,  
 mm 11 (57.1%),  
 9 (42.9%) ( 1).

4. 가 10 (47.6%),  
 GMFM foot print

1.		(n = 21)
		%
	15	71.4
	6	28.6
	21	100.0
	13	61.9
	6	28.6
	2	9.5
	21	100.0
	10	47.6
	11	52.4
	21	100.0
SPR	12	57.1
	9	42.9
	21	100.0

2.		( : (%))	
SPR	10(47.6)	2( 9.5)	12( 57.1)
SPR	0( 0.0)	9(42.9)	9( 42.9)
	10(47.6)	11(52.4)	21(100.0)

3.		(n = 21)
( )	(cm)	(cm)
73.11 ± 30.06	103.82 ± 12.61	51.39 ± 8.90

2 (9.5%) , 가 ( 2).  
 , 73.11 ± 30.06  
 (42.9%) . 9 , 103.82 ± 12.61 cm ,  
 51.39 ± 8.90 cm ( 3).

2. GMFM

. GMFM

가. GMFM  
GMFM

GMFM

( 4).

, (80),  
(.76), (.75), (.67),  
(.64) 가  
, GMFM

4. GMFM

GMFM	A	B	C	D	E
.76**	.32	.48*	.65**	.77**	.73**
.80**	.37	.56**	.70**	.82**	.76**
.75**	.41	.40	.34**	.73**	.75**
.64**	.41	.39	.53*	.62**	.64**
.67**	.29	.30	.57**	.66**	.67**
.30	.27	.30	.12	.29	.35

\* p<.05, \*\* p<.01

5. GMFM

(n = 21)

		±		
GMFM	(%)	78.33 ± 16.05	53	98.4
A	(%)	98.29 ± 2.31	92	100
B	(%)	98.81 ± 2.20	92	100
C	(%)	87.67 ± 13.75	60	100
D	(%)	60.81 ± 32.19	10	100
E	, , (%)	46.10 ± 34.89	0	97
	(m/s)	.28 ± .21	.06	.82
	(step/s)	1.22 ± .75	.28	2.83
	(m)	.91 ± .22	.59	1.32
	(m)	.45 ± .13	.20	.68
	(m)	.45 ± .11	.28	.67
	(mm)	157.62 ± 48.59	78	238

가 , B (56), A 가 , A, B GMFM ,  
 (.48) 가 , C C, D, E  
 (.70), (.65), 가 ( 5).  
 (.57), (.53), (.34) GMFM  
 가 D (.82), GMFM  
 (.77), (.73), (.66), , A, B, C, D, E  
 (.62) 가 , 가  
 (.76), (.75), (.73), E GMFM D( ) .  
 (.67), (.64) D .77  
 59.4% (R<sup>2</sup> = .594) .

6. GMFM

GMFM	A	B	C	D	E
.39	.44	.56	.07	.40	.51
.59	.49	.68*	.37	.49	.52
.22	.48	.16	.00	.02	.67*
.14	.34	-.03	.00	.04	.69*
.03	.13	-.20	-.06	-.18	.19
-.08	.27	.34	-.47	-.05	.03

\* p < .05

7. GMFM

GMFM	A	B	C	D	E
.38	-.52	.00	.62*	.42	.37
.22	-.50	.00	.41	.40	.19
.42	-.53	.00	.51	.42	.42
.35	-.40	.00	.07	-.05	.05
.45	-.52	.00	.54	.52	.46
.55	.16	.00	.57	.43	.55

\* p < .05



가 GMFM D 3. GMFM  
 ( ) . D .82 66.4% (R<sup>2</sup>  
 = .664) . 가 가. GMFM  
 GMFM . GMFM GMFM  
 .75 ,  
 56.0% (R<sup>2</sup> = .560) . 가 GMFM  
 GMFM E( , , 가 ( 7).  
 ) . E , , B (.68), E  
 .35 ,  
 12.1% (R<sup>2</sup> = .121) 가 ( 6). (.67), (.69)  
 가 ( 8).

8. (n = 21)

	SPR	(n = 12)	SPR	(n = 9)	p
GMFM (%)		89.80 ± 10.55 <sup>a</sup>	63.04 ± 5.54 <sup>a</sup>		.000**
A. (%)		99.50 ± 1.24	96.67 ± 2.45		.003**
B. (%)		100.00 ± .00	97.22 ± 2.68		.002**
C. (%)		96.17 ± 7.09	76.33 ± 12.26		.000**
D. (%)		82.83 ± 21.37	31.44 ± 16.29		.000**
E. , , (%)		70.50 ± 25.99	13.56 ± 5.41		.000**
(m/s)		.40 ± .20	.13 ± .07		.001**
(steps/s)		1.68 ± .64	.61 ± .36		.000**
(m)		1.04 ± .18	.74 ± .12		.000**
(m)		.53 ± .11	.34 ± .08		.000**
(m)		.50 ± .12	.40 ± .06		.028 <sup>a</sup>
(mm)		163.83 ± 54.91	149.33 ± 40.29		.513
( )		53.37 ± 15.23	99.43 ± 24.00		.000**
(cm)		95.86 ± 7.30	114.43 ± 10.12		.000**
(cm)		46.77 ± 6.52	57.56 ± 8.05		.003**

\* p < .05, \*\* p < .01 <sup>a</sup> ±

GMFM

4.

GMFM

가.  
 GMFM  
 , A, B, C, C (.62) 가  
 D, E, , , ( 10).  
 , 가 (.84), (.77)  
 ( 9). 가 ( 11).

9. GMFM

	X-Y	R <sup>2</sup>	tolerance	Durbin-Watson (d)
Y( ) = -0.02388 + 0.005013 × X( D)	.77	.594	1.000	2.556
Y( ) = -0.06327 + 0.01905 × X( D)	.82	.664	1.000	3.000
Y( ) = 0.121 + 0.01012 × X(GMFM )	.75	.560	1.000	1.947
Y( ) = 135.312 + 0.484 × X( E)	.35	.121	1.000	2.301

10. GMFM

GMFM	A	B	C	D	E
-.09	-.53	.00	.29	-.01	-.10
-.35	-.49	.00	-.11	-.04	-.40
.07	-.55	.00	.21	.06	.07
-.03	-.45	.00	-.02	-.15	-.01
.09	-.53	.00	.23	.21	.11
.56	.23	.00	.52	.40	.58

11.

GMFM

GMFM	A	B	C	D	E
.30	.53	.57	-.12	.35	.44
.43	.39	.52	.17	.35	.38
.30	.52	-.02	.09	.12	.84**
.07	.19	-.38	.04	.04	.77*
.08	.55	.02	-.13	-.21	.49
.00	.40	.50	-.44	.10	.18

\*p<.05, \*\*p<.01

12.

(n = 21)

		(n = 10)	(n = 11)	p
GMFM	(%)	93.88 ± 4.36 <sup>a</sup>	64.20 ± 6.05 <sup>a</sup>	.000**
A.	(%)	99.40 ± 1.35	97.27 ± 2.57	.031*
B.	(%)	100.00 ± .00	97.73 ± 2.65	.014*
C.	(%)	98.80 ± 2.10	77.55 ± 11.72	.000**
D.	(%)	91.50 ± 5.30	32.91 ± 15.79	.000**
E.	(%)	79.70 ± 15.78	15.55 ± 7.37	.000**
	(m/s)	.45 ± .18	.13 ± .06	.000**
	(step/s)	1.85 ± .55	.65 ± .34	.000**
	(m)	1.09 ± .16	.76 ± .12	.000**
	(m)	.54 ± .09	.37 ± .11	.001**
	(m)	.53 ± .09	.38 ± .07	.000**
	(mm)	171.70 ± 57.14	144.82 ± 37.49	.214
	( )	55.39 ± 16.00	89.21 ± 31.26	.006**
	(cm)	97.60 ± .56	109.47 ± 14.33	.027*
	(cm)	47.92 ± .53	54.55 ± 9.85	.088

\*p<.05, \*\* p<.01 <sup>a</sup> ±

13.

( : %)

				SPR	SPR
GMFM	20.49	4.64	9.42	11.75	8.79
A.	2.35	1.36	2.64	1.25	2.53
B.	2.23	.00	2.71	.00	2.76
C.	15.68	2.13	15.11	7.37	16.06
D.	52.94	5.79	47.98	25.80	51.81
E. , ,	75.68	19.80	47.40	36.87	39.90

. GMFM A, B ( 13).

가 . GMFM A, GMFM  
 B, C, D, E, 가 GMFM  
 , , , 가  
 (Damiano Abel, 1996).  
 GMFM

( 12).

foot print

, GMFM

5.

A, B, C, 가  
 D, E (coefficient variation; CV)<sup>1)</sup> 2.35%, 2.23%, 15.6 가 , , 가  
 8%, 52.94%, 75.68% .  
 E(75.68%) 가 가 가 ( , 1994).  
 , D(52.94%), GMFM (20.49), 가  
 C(15.68) 가  
 D, E , 가 , 가 .  
 5.79%, 19.80%, 25.80%, 가  
 36.87% D, E  
 52.94%, 75.68% . , 가 , 가 .

1) (%) = / × 100

가 , E ,

가 ,

GMFM 가

A( ), B( ) D, E가

C( ), D( )

), E( , )

가 , A, B

GMFM

C 가

D, E

GMFM C, D, E 가 GMFM 가

가 , GMFM 가

가 GMFM 가

GMFM 가

GMFM 가 , GMFM GMFM

가 , GMFM 가

GMFM 가

GMFM , 가

GMFM GMFM

GMFM , GMFM

(.80), (.76), (.75),

(.67), (.64)

가 Damiano Abel

(1996) GMFM (.79),

(.72), (.60) Damiano Abel(1996) GMFM

가

GMFM

A 가

B , 가

C ,

가

B , D

가

(quantity) 가

(quality) 가

가

가 GMFM  
foot print , GMFM  
, 가 가  
GMFM D, 가 가 ,  
가 GMFM E .  
Damiano Abel(1996) GMFM 21  
, 가  
(motor status) 가  
. 1. GMFM  
, 가 , , ,  
GMFM 가 , GMFM  
GMFM A(  
), B( ), C( )  
D( ), E( , , )  
가 GMFM 가  
foot print . 2.  
GMFM , 가 가 GMFM  
D( ) , 가 가  
가 가 GMFM ,  
E( , , ) GMFM  
가 , GMFM  
GMFM , GMFM  
, GMFM  
가  
, 가  
가 GMFM  
, GMFM

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